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Linear Chaos in Lipschitz-free spaces

Based on a joint work with Alfred Peris

Christian Cobollo

New Perspectives in Banach Spaces and Banach Lattices
11th July, 2024.

Sponsors (so I don't go to jail :))

The author is supported by:

MCIN/AEI/10.13039/501100011033

- PID2021-122126NB-C33
- PID2019-105011GB-I00
- PID2022-139449NB-I00

Generalitat Valenciana

- PROMETEU/2021/070
- CIACIF/2021/378



Lipschitz-free Preliminaries

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The **Lipschitz-free space** of M is defined as

$$\mathcal{F}(M) := \overline{\text{span}}\{\delta_x : x \in M\} \ (\subset \text{Lip}_0(M)^*),$$

and it is indeed a predual of $\text{Lip}_0(M)$.

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Roughly speaking, we can think of $\mathcal{F}(M)$ as taking M and providing it with a linear structure in which distinct (non-zero) points in M are now linearly independent, and the endowed norm is the one keeping the original metric structure of M . Thus, $\|\delta_x\| = d(x, 0)$, or more generally, $\|\delta_x - \delta_y\| = d(x, y)$.

Lipschitz-free Preliminaries

Why is $\mathcal{F}(M)$ so special?

The Universal Property (Linearization)

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$$f \in \text{Lip}_0(M, X)$$

$$\begin{array}{ccc} M & \xrightarrow{f} & X \\ \delta \downarrow & & \nearrow T_f \\ \mathcal{F}(M) & & \end{array}$$

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Then, given $f \in \text{Lip}_0(M, M)$, what about $T_f \in \mathcal{L}(\mathcal{F}(M))$?

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-  Andrés' talk (Tuesday)!

Linear Dynamics

The properties we like

Definition

f is **hypercyclic** if:

$\exists x \in M : \text{Orb}(x, f)$ is dense.

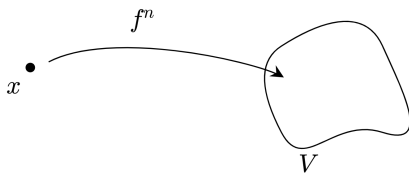
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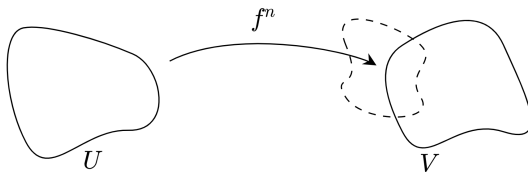
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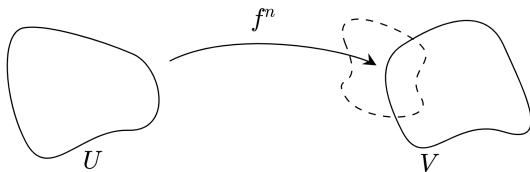
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f is **mixing** if:

For $U, V \subset M$ open, $\exists n_0 \in \mathbb{N} : f^n(U) \cap V \neq \emptyset, \forall n \geq n_0$



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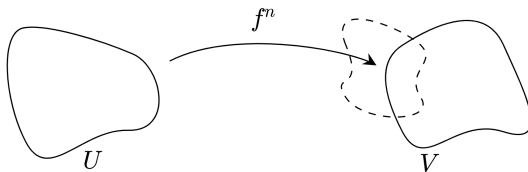
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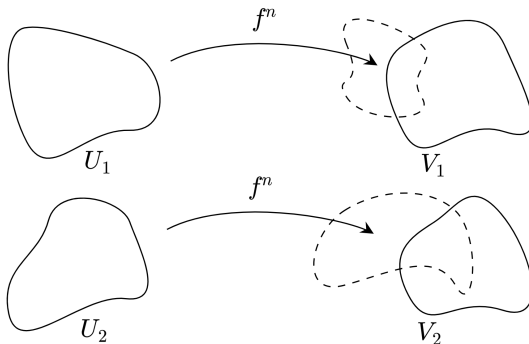
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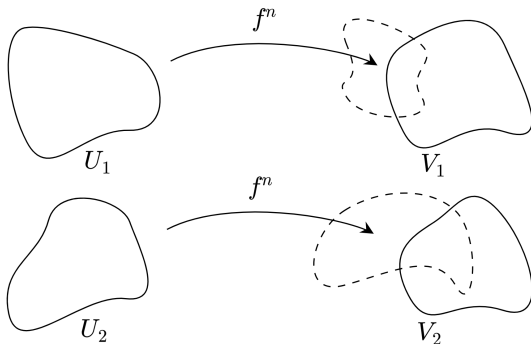
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f is **weakly mixing** if:

For $U_1, U_2, V_1, V_2 \subset M$ open, $\exists n \in \mathbb{N} : f^n(U_1) \cap V_1 \neq \emptyset, f^n(U_2) \cap V_2 \neq \emptyset$



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$$\text{mixing} \implies \text{weakly mixing} \implies \text{transitive}$$

Linear Dynamics in $\mathcal{F}(M)$

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Theorem (A. Peris, M. Murillo-Arcila, 2015)

Let $T \in \mathcal{L}(X)$ and $K \subset X$ a T -invariant set, $0 \in K$, $\overline{\text{span}(K)} = X$. If $T|_K$ is weakly mixing, weakly mixing and chaotic, or mixing, then T has the same property.

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Example: Let $T_f \in \mathcal{L}(\mathcal{F}(M))$, $\delta(M) \in \mathcal{F}(M)$ is T_f -invariant, $0 \in \delta(M)$, and $\overline{\text{span}(\delta(M))} = \mathcal{F}(M)$. But, $T_f(\delta_x) = \delta_{f(x)}$.

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Corollary

If $f \in \text{Lip}_0(M, M)$ is weakly mixing, weakly mixing and chaotic, or mixing, then $T_f \in \mathcal{L}(\mathcal{F}(M))$ has the same property.

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Proposition (Abbar, Coine, Petitjean, 2021)

Let M be a metric space with non-isolated $0 \in M$, and $f \in \text{Lip}_0(M, M)$. TFAE:

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Proof.

Idea:

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Idea: Dense in a linearly dense \implies linearly dense. □

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We will see—in a quite more general set-up—that every “strong enough” property is inherited from M to $\mathcal{F}(M)$.

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A way to define your own transitivity!

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- (iii) If $A, B \in \mathcal{A}$ then $A \cap B \in \mathcal{A}$,
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Let f be a map in M , $\mathcal{A} \subset \mathcal{P}(\mathbb{N})$ a Furstenberg family. We say that f is \mathcal{A} -transitive if for every U, V open sets,

$$N_f(U, V) \in \mathcal{A}.$$

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Notation

If we are considering several maps f_1, \dots, f_N on M , and open sets $U_1, \dots, U_N \subset M$,

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If we are considering several maps f_1, \dots, f_N on M , and open sets $U_1, \dots, U_N \subset M$, (please) allow us to denote

$$f := f_1 \times f_2 \times \dots \times f_N$$

$$U := U_1 \times \dots \times U_N$$

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f_1, \dots, f_N are **disjoint transitive** if for every $U_0, U_1, \dots, U_N \subset M$ open,

$$d\mathcal{N}_f(U_0, U) := \{n \in \mathbb{N} : U_0 \cap \bigcap_{i=1}^N f_i^{-n}(U_i) \neq \emptyset\} \neq \emptyset$$

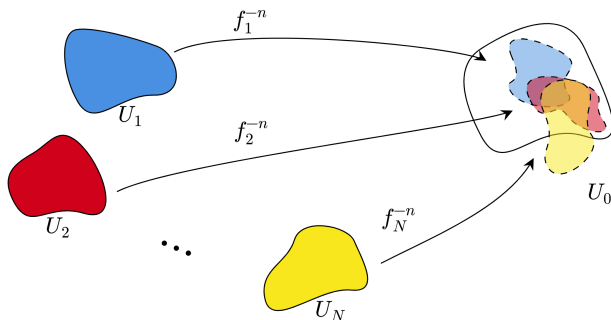
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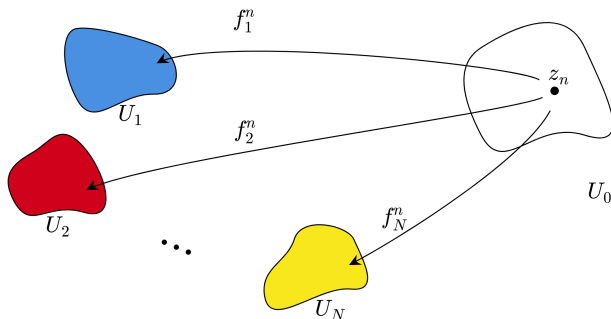
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Let M (no isolated points) and f_1, \dots, f_N . Then, $d\mathcal{N}_f(U_0, U) \neq \emptyset$ if and only if $d\mathcal{N}_f(U_0, U)$ is infinite.

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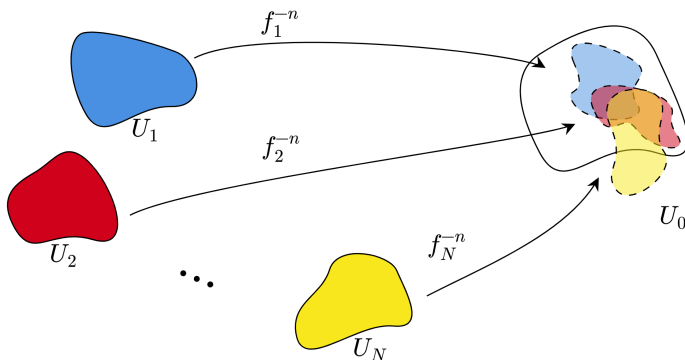
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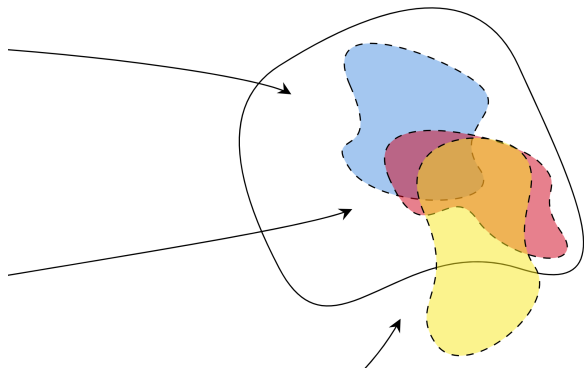


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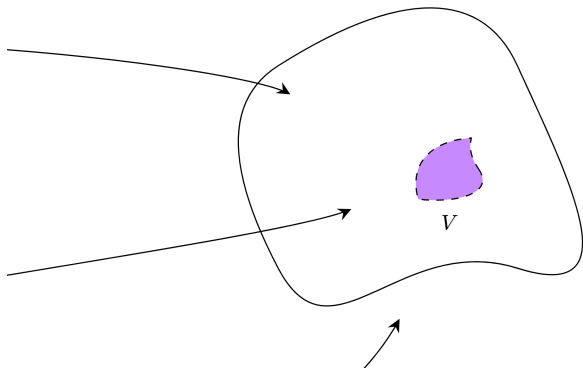


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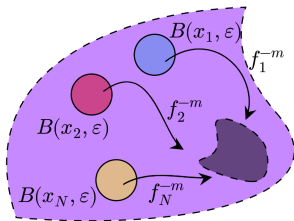


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Idea: You can always procrastinate



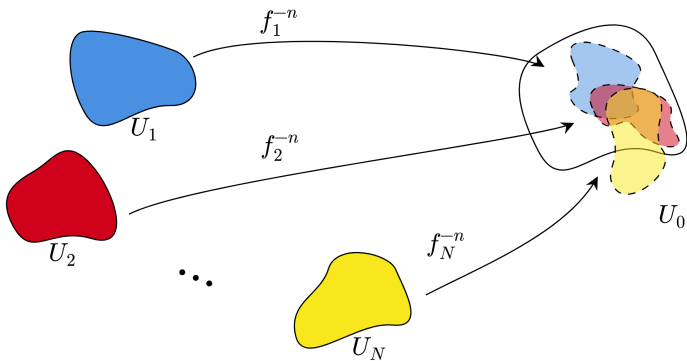
V

Linear Dynamics in $\mathcal{F}(M)$

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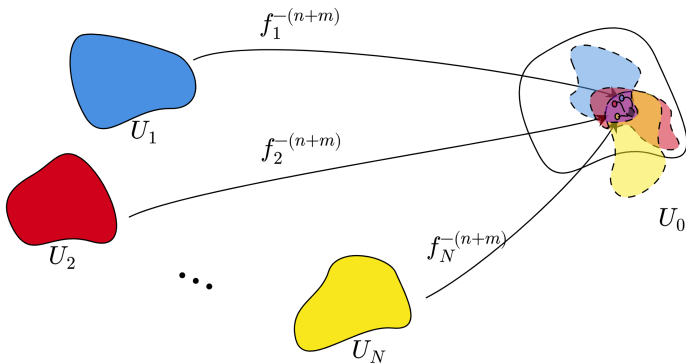


Linear Dynamics in $\mathcal{F}(M)$

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Linear Dynamics in $\mathcal{F}(M)$

Definition

Let f_1, \dots, f_N maps defined in M , $\mathcal{A} \subset \mathcal{P}(\mathbb{N})$ be a Furstenberg family. We say that f_1, \dots, f_N are **disjoint \mathcal{A} -transitive** if for every non-empty open subsets $U_0, U_1, \dots, U_N \subset M$

$$d\mathcal{N}_f(U_0, U) \in \mathcal{A}.$$

Linear Dynamics in $\mathcal{F}(M)$

Inheritance of strong properties

Theorem (Ch. C. and A. Peris, 2024+)

Let $f_1, \dots, f_N \in \text{Lip}_0(M, M)$ disjoint \mathcal{A} -transitive maps in M , with \mathcal{A} being a filter. Then its corresponding operators $T_{f_1}, \dots, T_{f_N} \in \mathcal{L}(\mathcal{F}(M))$ are disjoint \mathcal{A} -transitive.

Linear Dynamics in $\mathcal{F}(M)$

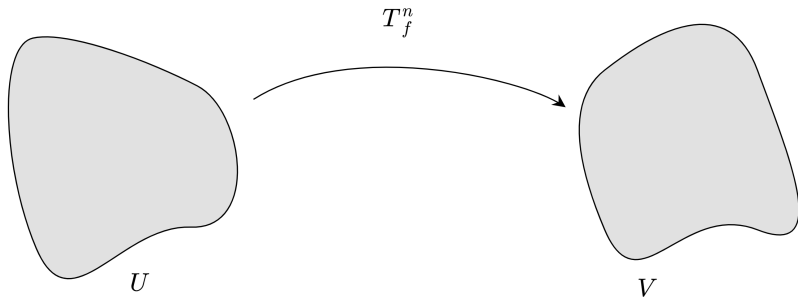
Inheritance of strong properties

Idea:

Linear Dynamics in $\mathcal{F}(M)$

Inheritance of strong properties

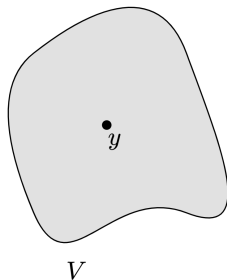
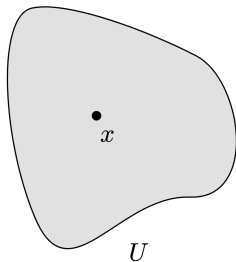
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Linear Dynamics in $\mathcal{F}(M)$

Inheritance of strong properties

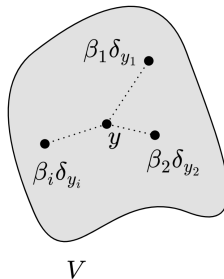
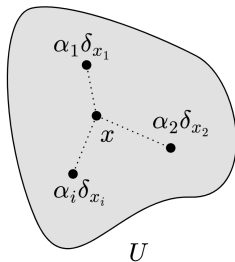
Idea:



Linear Dynamics in $\mathcal{F}(M)$

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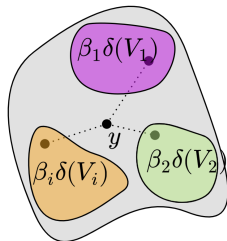
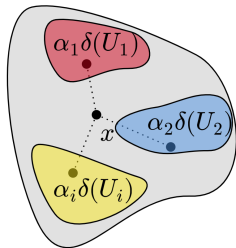
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Linear Dynamics in $\mathcal{F}(M)$

Inheritance of strong properties

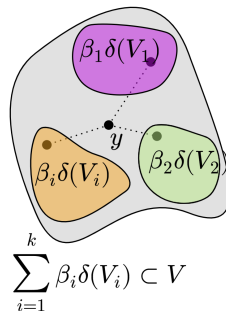
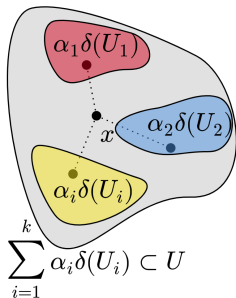
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Linear Dynamics in $\mathcal{F}(M)$

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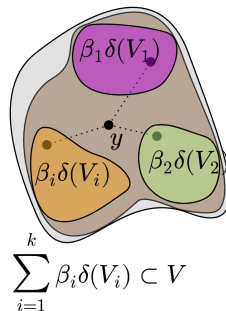
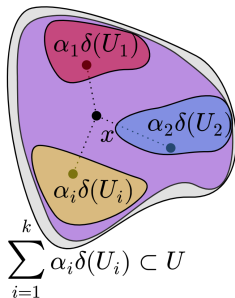
Idea:



Linear Dynamics in $\mathcal{F}(M)$

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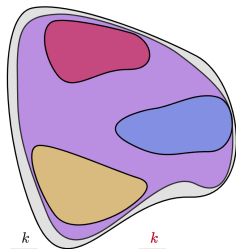
Idea:



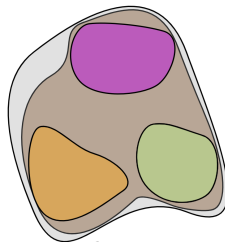
Linear Dynamics in $\mathcal{F}(M)$

Inheritance of strong properties

Idea:



$$\sum_{i=1}^k \alpha_i \delta(U_i) + \sum_{i=1}^k \beta_i \delta(W_0) \subset U$$

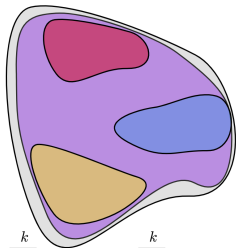


$$\sum_{i=1}^k \alpha_i \delta(W_0) + \sum_{i=1}^k \beta_i \delta(V_i) \subset V$$

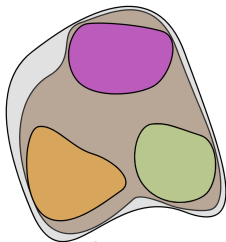
Linear Dynamics in $\mathcal{F}(M)$

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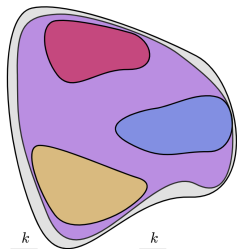
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Linear Dynamics in $\mathcal{F}(M)$

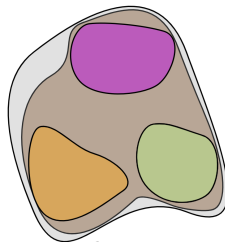
Inheritance of strong properties

Idea:

$$U_i \xrightarrow{f} W_0$$



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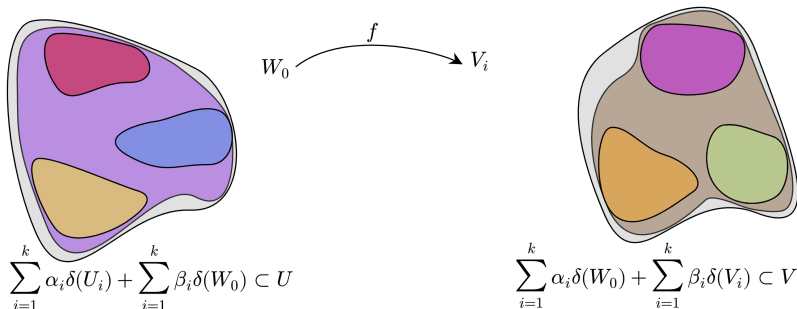


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Linear Dynamics in $\mathcal{F}(M)$

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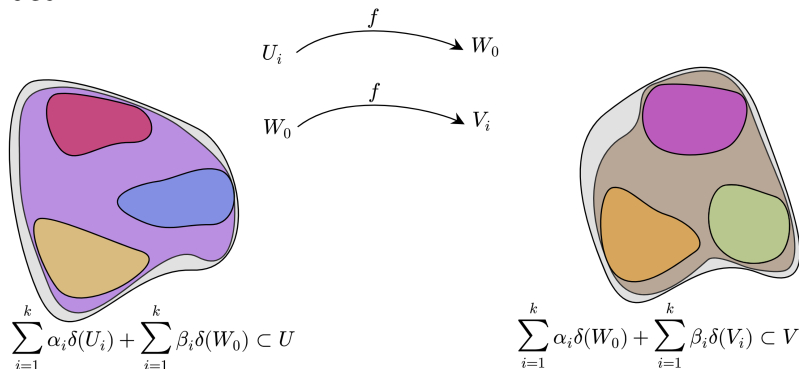
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Linear Dynamics in $\mathcal{F}(M)$

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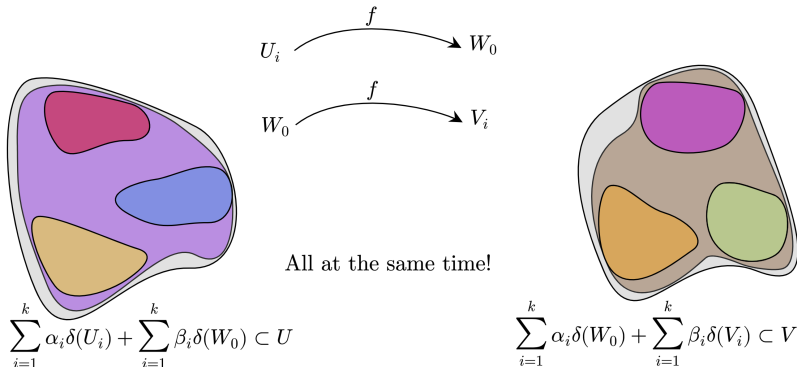
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Linear Dynamics in $\mathcal{F}(M)$

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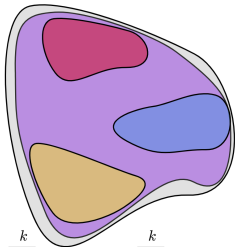


Linear Dynamics in $\mathcal{F}(M)$

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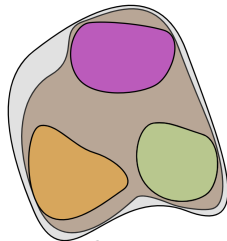
Idea:

$$\bigcap_{i=1}^k (N_f(U_i, W_0) \cap N_f(W_0, V_i))$$



$$\sum_{i=1}^k \alpha_i \delta(U_i) + \sum_{i=1}^k \beta_i \delta(W_0) \subset U$$

All at the same time!



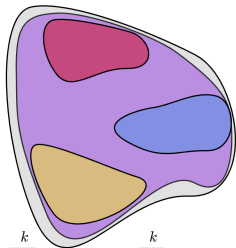
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Linear Dynamics in $\mathcal{F}(M)$

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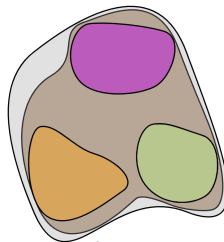
Idea:

$$\bigcap_{i=1}^k (N_f(U_i, W_0) \cap N_f(W_0, V_i)) \in \mathcal{A}$$



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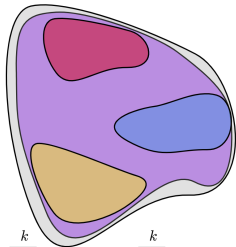
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Linear Dynamics in $\mathcal{F}(M)$

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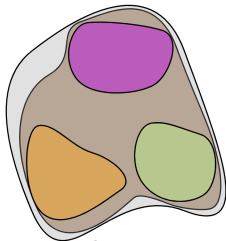
Idea:

$$N_{T_f}(U, V) \supset \bigcap_{i=1}^k (N_f(U_i, W_0) \cap N_f(W_0, V_i)) \in \mathcal{A}$$



$$\sum_{i=1}^k \alpha_i \delta(U_i) + \sum_{i=1}^k \beta_i \delta(W_0) \subset U$$

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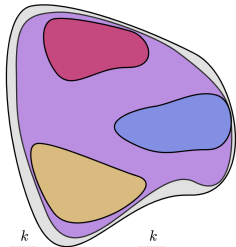
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Linear Dynamics in $\mathcal{F}(M)$

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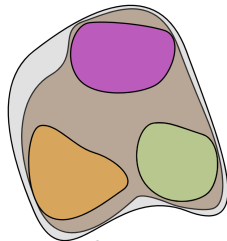
Idea:

$$n \in \bigcap_{i=1}^k (N_f(U_i, W_0) \cap N_f(W_0, V_i)) \in \mathcal{A}$$



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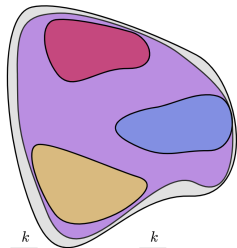
Linear Dynamics in $\mathcal{F}(M)$

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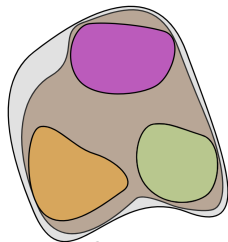
$$n \in \bigcap_{i=1}^k (N_f(U_i, W_0) \cap N_f(W_0, V_i)) \in \mathcal{A}$$

T_f^n



All at the same time!

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Linear Dynamics in $\mathcal{F}(M)$

Inheritance of strong properties

Theorem (Ch. C. and A. Peris, 2024+)

Let $f_1, \dots, f_N \in \text{Lip}_0(M, M)$ disjoint \mathcal{A} -transitive maps in M , with \mathcal{A} being a filter. Then its corresponding operators $T_{f_1}, \dots, T_{f_N} \in \mathcal{L}(\mathcal{F}(M))$ are disjoint \mathcal{A} -transitive.

Linear Dynamics in $\mathcal{F}(M)$

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Corollary (Ch. C. and A. Peris, 2024+)

Let $f \in \text{Lip}_0(M, M)$ \mathcal{A} -transitive map in M , with \mathcal{A} being a filter. Then its corresponding operator $T_f \in \mathcal{L}(\mathcal{F}(M))$ is \mathcal{A} -transitive.

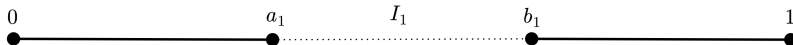
Linear Dynamics in $\mathcal{F}(M)$

Backward Shift on the Cantor set

Linear Dynamics in $\mathcal{F}(M)$

Backward Shift on the Cantor set

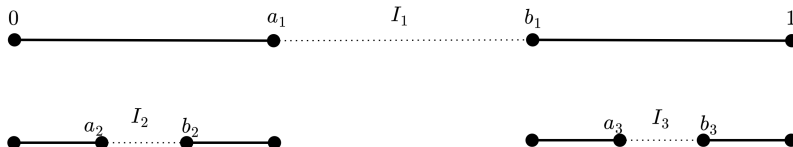
Let \mathcal{C} be the middle third ternary Cantor set.



Linear Dynamics in $\mathcal{F}(M)$

Backward Shift on the Cantor set

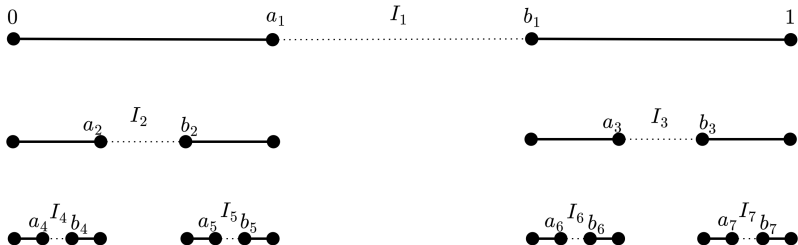
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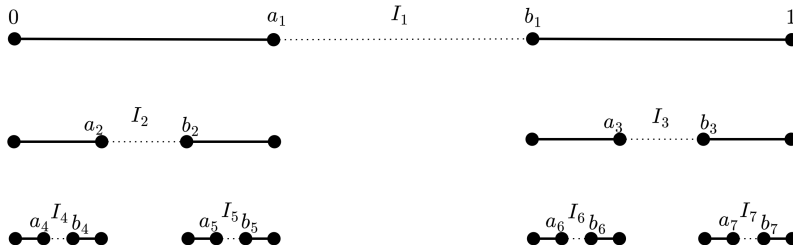
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Linear Dynamics in $\mathcal{F}(M)$

Backward Shift on the Cantor set

Let \mathfrak{C} be the middle third ternary Cantor set.



Thus, $\mathfrak{C} = [0, 1] \setminus (\bigcup_{n=1}^{\infty} I_n)$.

Linear Dynamics in $\mathcal{F}(M)$

Backward Shift on the Cantor set

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Linear Dynamics in $\mathcal{F}(M)$

Backward Shift on the Cantor set

Thus, $\mathfrak{C} = [0, 1] \setminus (\bigcup_{n=1}^{\infty} I_n)$.

$$(d(b_n, a_n))_{n=1}^{\infty} = \left(\frac{1}{3}, \frac{1}{3^2}, \frac{1}{3^2}, \frac{1}{3^3}, \frac{1}{3^3}, \frac{1}{3^3}, \frac{1}{3^3}, \dots \right),$$

Linear Dynamics in $\mathcal{F}(M)$

Backward Shift on the Cantor set

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Every $t \in \mathfrak{C}$ has a ternary representation as a sequence of 0's and 2's, $s(t) := (s_1(t), s_2(t), \dots)$ such that $t = \sum \frac{s_n(t)}{3^n}$ (where $s_n(t) \in \{0, 2\}$).

Linear Dynamics in $\mathcal{F}(M)$

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Now, consider the (Lipschitz) map $\sigma: \mathfrak{C} \rightarrow \mathfrak{C}$ known as the **backward shift**, defined by the expression

$$\sigma(t) := \sum \frac{s_{n+1}(t)}{3^n}.$$

Linear Dynamics in $\mathcal{F}(M)$

Backward Shift on the Cantor set

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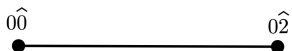
$$(s_1(t), s_2(t), s_3(t), \dots) \xrightarrow{\sigma} (s_2(t), s_3(t), \dots)$$

Linear Dynamics in $\mathcal{F}(M)$

Backward Shift on the Cantor set

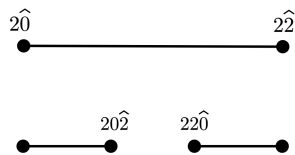
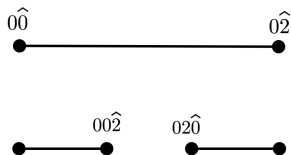
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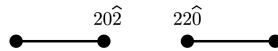
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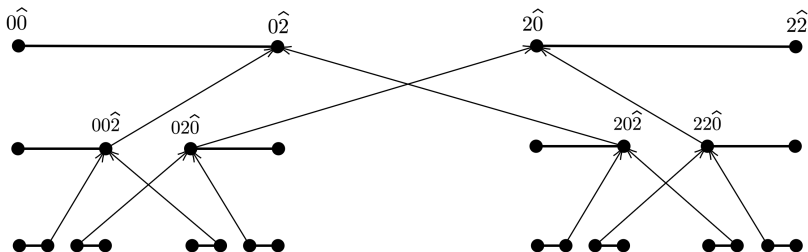
Linear Dynamics in $\mathcal{F}(M)$

Backward Shift on the Cantor set



Linear Dynamics in $\mathcal{F}(M)$

Backward Shift on the Cantor set



Linear Dynamics in $\mathcal{F}(M)$

Backward Shift on the Cantor set

Proposition (Ch. C. and A. Peris, 2024+)

The operator $T_\sigma \in \mathcal{L}(\mathcal{F}(\mathfrak{C}))$ is conjugated to $S_\sigma \in \mathcal{L}(\ell_1)$ such that $S_\sigma(e_n) = 3e_{[n/2]}$ for $n \geq 2$, and $S_\sigma(e_1) = -3 \sum_{n=1}^{\infty} d(b_n, a_n)e_n$ (which, moreover, is a fixed point).

Linear Dynamics in $\mathcal{F}(M)$

Backward Shift on the Cantor set

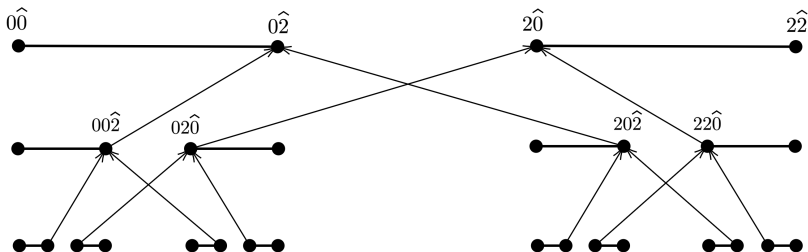
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$$M_\sigma = 3 \begin{bmatrix} -d_1 & 1 & 1 & 0 & 0 & 0 & 0 & \cdots \\ -d_2 & 0 & 0 & 1 & 1 & 0 & 0 & \cdots \\ -d_3 & 0 & 0 & 0 & 0 & 1 & 1 & \cdots \\ \vdots & \vdots & & & \ddots & \ddots & & \ddots \end{bmatrix}$$

Linear Dynamics in $\mathcal{F}(M)$

Backward Shift on the Cantor set



Linear Dynamics in $\mathcal{F}(M)$

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Proposition (Ch. C. and A. Peris, 2024+)

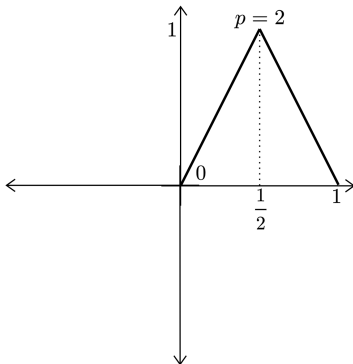
Let $\sigma : \mathfrak{C} \rightarrow \mathfrak{C}$ be the backward shift map in the usual ternary Cantor set. Therefore $T_{\sigma^{m_1}}, \dots, T_{\sigma^{m_N}}$ are disjoint mixing operators in $\mathcal{F}(\mathfrak{C})$.

Linear Dynamics in $\mathcal{F}(M)$

“What if I’m not strong?” The anti-symmetric tent map

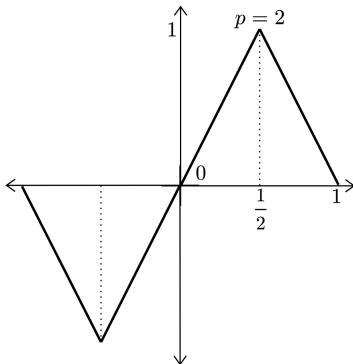
Linear Dynamics in $\mathcal{F}(M)$

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Linear Dynamics in $\mathcal{F}(M)$

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Linear Dynamics in $\mathcal{F}(M)$

“What if I’m not strong?” The anti-symmetric tent map

Proposition (Ch. C. and A. Peris, 2024+)

Let f be the anti-symmetric tent map in $[-1, 1]$. Therefore $T_{f^{m_1}}, \dots, T_{f^{m_N}}$ are disjoint mixing operators in $\mathcal{F}([-1, 1])$.

Linear Dynamics in $\mathcal{F}(M)$

“What if I’m not strong?” The anti-symmetric tent map

Proposition (Ch. C. and A. Peris, 2024+)

Let f be the anti-symmetric tent map in $[-1, 1]$. Therefore $T_{f^{m_1}}, \dots, T_{f^{m_N}}$ are disjoint mixing operators in $\mathcal{F}([-1, 1])$. Although f (and no power of f) is even transitive!

Linear Dynamics in $\mathcal{F}(M)$

Lipschitz Disjoint Hypercyclicity Criterion

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- 1 $f_i^{n_k}(x_0) \xrightarrow{k \rightarrow \infty} 0$ for every $x_0 \in M_0$.
- 2 $g_{i,k}(x_i) \xrightarrow{k \rightarrow \infty} 0$ for every $x_i \in M_i$.

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- ❸ $(f_i^{n_k} \circ g_{j,k})(x_i) \xrightarrow{k \rightarrow \infty} \begin{cases} x_i & \text{if } j = i; \\ 0 & \text{if } j \neq i; \end{cases}$ for every $x_i \in M_i$.

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Then T_{f_1}, \dots, T_{f_N} satisfy the d-Hypercyclicity Criterion (Bès, Peris, 2007).

Linear Dynamics in $\mathcal{F}(M)$

Lipschitz d-Hypercyclicity Criterion

Corollary

If $N = 1$, Lipschitz Hypercyclicity Criterion (Abbar, Coine, Petitjean, 2021).

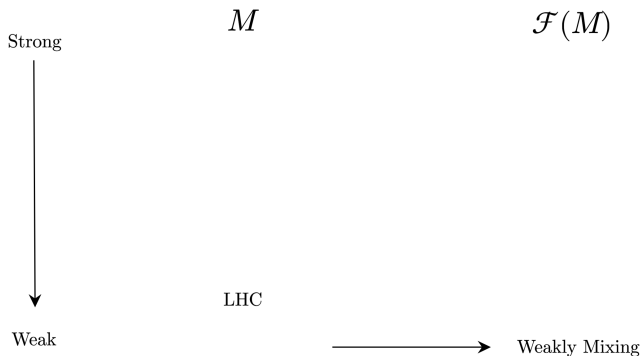
Just a glimpse

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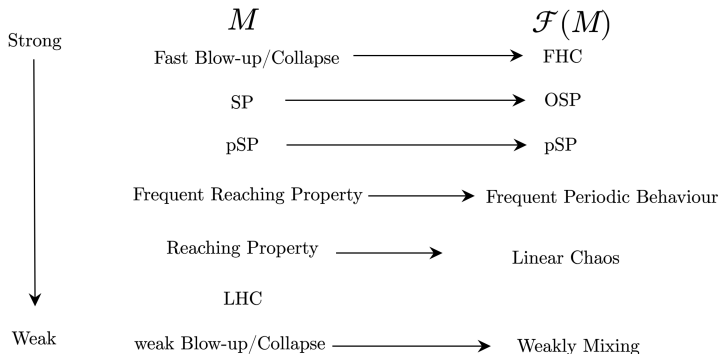
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Some references

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The End

Thanks For Your Attention!